



TITLE:

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CITATION:

Barré, J. ...[et al]. Trapping scaling for bifurcations in the Vlasov systems. Physical Review E 2016, 93(4): 042207.

ISSUE DATE:

2016-04-14

URL:

<http://hdl.handle.net/2433/210248>

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Trapping scaling for bifurcations in the Vlasov systems

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(Received 25 November 2015; published 14 April 2016)

We study nonoscillating bifurcations of nonhomogeneous steady states of the Vlasov equation, a situation occurring in galactic models, or for Bernstein–Greene–Kruskal modes in plasma physics. Through an unstable manifold expansion, we show that in one spatial dimension the dynamics is very sensitive to the initial perturbation: the instability may saturate at small amplitude—generalizing the “trapping scaling” of plasma physics—or may grow to produce a large-scale modification of the system. Furthermore, resonances are strongly suppressed, leading to different phenomena with respect to the homogeneous case. These analytical findings are illustrated and extended by direct numerical simulations with a cosine interaction potential.

DOI: [10.1103/PhysRevE.93.042207](https://doi.org/10.1103/PhysRevE.93.042207)

I. INTRODUCTION

The Vlasov equation models the dynamics of a large number of interacting particles when the force acting on them is dominated by the mean field. It is a fundamental equation of plasma physics and galactic dynamics, but also describes a number of other physical systems, such as wave-particles interactions [1], free electron lasers [2], certain regimes of nonlinear optics [3], and wave propagation in bubbly fluids [4]. Understanding its qualitative behavior has proved to be a formidable challenge, from the first linear computations of Landau [5] to the most recent mathematical breakthroughs [6]. We address here a problem of bifurcations in these systems.

The study of the bifurcation of *homogeneous* stationary solutions to the Vlasov equation (when particles are homogeneously distributed in space with a certain velocity distribution) has a long and interesting history, mainly related to plasma physics; a detailed account can be found in Ref. [7]. One of the main question is to determine the asymptotic behavior of the system, when started close to an unstable stationary state. The basic mechanism, ultimately responsible for the instability saturation, is the *resonance* phenomenon: particles with a velocity close to that of the growing mode are strongly affected by the small perturbation. This was qualitatively recognized in the 1960s [8–10], leading these authors to predict the famous “trapping scaling,” that is the asymptotic electric field, after nonlinear saturation, would be of order λ^2 , with λ being the instability rate. However, formal computations relying on standard nonlinear expansions often led to the very different $\lambda^{1/2}$ scaling (see discussion and references in Ref. [7]). In the 1990s, Crawford’s careful unstable manifold computations finally recovered unambiguously the trapping scaling [11]. Yet his expansion is plagued by strong divergences in the $\lambda \rightarrow 0^+$ limit. Soon after, del-Castillo-Negrete derived an infinite-dimensional reduced model for the instability development by using different techniques [12]. This is currently the best understanding we have and shows a striking degree of universality.

Understanding the nonhomogeneous case is further challenging and has a practical importance for various physical systems. A first key example comes from astrophysics. The radial orbit instability destabilizes a spherical self-gravitating

system when the number of low-angular-momentum particles, usually stars, grows. The fate of the initially unstable system has been qualitatively and numerically studied in Ref. [13], providing a rare example of such a bifurcation study. In the plasma physics context, Bernstein–Greene–Kruskal exhibited a large family of exact solutions of the Vlasov–Poisson equation [14], now commonly called BGK modes. Some of these solutions are stable, others unstable [15–18]. The nonlinear behavior in case of instability is an open question.

To tackle the bifurcation in the nonhomogeneous case we will consider in this article as a first step the case of a real unstable eigenvalue for a one-dimensional system. We will show that the number of particles around zero frequency is negligible in the nonhomogeneous case compared with the homogeneous case. This is a crucial remark since it implies that, for nonoscillating instabilities, the resonance phenomenon will be absent or strongly suppressed. Nevertheless, similarly to the homogeneous case, the unstable eigenvalue still bifurcates from a marginally stable continuous spectrum. Thus, one should expect a new type of bifurcation. Our strategy is to attack this problem by revisiting Crawford’s expansion to describe the dynamics on the unstable manifold. The following basic questions arise: Does the instability saturate at small amplitude? What is the analog of the trapping scaling? Can we expect the same kind of universality as in the homogeneous context? Our main results include the following: (i) A striking asymmetry on the unstable manifold: one branch leads to a small-amplitude saturation, the other escapes far from the original stationary point. (ii) The λ^2 trapping scaling, well known in the homogeneous case, generalizes for the small-amplitude saturation; however, the reason for this scaling is very different. This result can also be reached by a different theoretical approach, following [19]. (iii) Since these features depend on some generic physical characteristic of the problem, we expect our results to be generic, at least for one-dimensional (1D) systems.

The outline of the article is as follows: Section II deals with a general one-dimensional Vlasov equation. We first explain formally how to obtain the unstable manifold expansion and emphasize the main physical points (Sec. II A), and then present a more detailed computation (Sec. II B). In Sec. III, we

restrict ourselves to a particular cosine interaction potential. We are then able to perform more explicit computations, provide precise predictions, as well as push the computations at higher orders, which is crucial to understand the divergence pattern of the expansion (Sec. III B). We also show how some of these predictions can also be obtained via the recently introduced “rearrangement-formula” idea [19], which provides an independent theoretical approach (Sec. III C). In Sec. IV, we compare all previous predictions with direct numerical simulations. The choice of the cosine potential allows us to perform very precise computations. Section V is devoted to some final comments and open questions.

II. UNSTABLE MANIFOLD REDUCTION (SPATIALLY PERIODIC ONE-DIMENSIONAL SYSTEMS)

A. General picture

The Vlasov equation associated with the one-particle Hamiltonian $H[f]$ is

$$\partial_t f = \{f, H[f]\}, \quad H[f](q, p, t) = p^2/2 + V[f](q, t), \quad (1)$$

where the one-particle potential $V[f]$ is defined by using the two-body interaction $v(q)$ as

$$V[f](q, t) = \int v(q - q') f(q', p', t) dq' dp', \quad (2)$$

and the Poisson bracket $\{\cdot, \cdot\}$ is

$$\{u, v\} = \partial_p u \partial_q v - \partial_q u \partial_p v. \quad (3)$$

Denote by f_μ a family of unstable stationary states depending on the parameter μ , and by g a perturbation around f_μ . The equation for g consists of a linear part and a nonlinear part:

$$\partial_t g = L_\mu g + N[g], \quad (4)$$

where

$$L_\mu g = \{g, H[f_\mu]\} + \{f_\mu, V[g]\}, \quad N[g] = \{g, V[g]\}. \quad (5)$$

Let L_μ have an unstable *real* nondegenerate eigenvalue λ depending on μ , and Ψ_λ be the corresponding eigenfunction. We assume that the family $\{f_\mu\}$ has a critical point μ_c , where the eigenvalue is $\lambda = 0$, and we study the system in the limit $\mu \rightarrow \mu_c$, which implies $\lambda \rightarrow 0^+$.

Notice that the Hamiltonian structure implies that L_μ also has the eigenvalue $-\lambda$. In addition, by space translation symmetry when f_μ is homogeneous in space, λ is in this case twice degenerate. When f_μ is nonhomogeneous, the symmetry is broken, and a neutral Goldstone mode Ψ_N appears.

We use the standard L^2 Hermitian product, and introduce L_μ^\dagger , which is the adjoint operator of L_μ , and $\tilde{\Psi}_\lambda$, which is the adjoint eigenfunction with eigenvalue $\lambda^* = \lambda$, where λ^* is the complex conjugate of λ . We normalize it as $\langle \tilde{\Psi}_\lambda, \Psi_\lambda \rangle = 1$, where the scalar product is defined by

$$\langle f, g \rangle = \int f^* g dq dp, \quad (6)$$

and denote by $\Pi_\mu(\cdot) = \langle \tilde{\Psi}_\lambda, \cdot \rangle \Psi_\lambda$ the projection onto the unstable eigenspace $\text{Span}\{\Psi_\lambda\}$. Depending on the behavior of $\Psi_{\pm\lambda}$ and Ψ_N when $\lambda \rightarrow 0^+$, Π_μ can be singular in this limit. As will become clear later on, this is the origin of an important

difference between the homogeneous and nonhomogeneous cases.

We are interested in the dynamics on the unstable manifold of f_μ and expand g as

$$g(q, p, t) = A(t) \Psi_\lambda(q, p) + S(q, p, A(t)). \quad (7)$$

The term S parametrizes the unstable manifold, and we have the estimate $S = O(A^2)$ for small A by assuming that the unstable manifold is tangent to the unstable eigenspace. Note that this parametrization may be only local.

Performing the projection, we obtain for $A(t)$ the following dynamical equation, expanded in powers of A :

$$\dot{A} = \lambda A + \langle \tilde{\Psi}_\lambda, N[f] \rangle = \lambda A + a_2(\lambda) A^2 + a_3(\lambda) A^3 + \dots, \quad (8)$$

where the coefficient a_2 is

$$a_2(\lambda) = \langle \tilde{\Psi}_\lambda, \{\Psi_\lambda, V[\Psi_\lambda]\} \rangle. \quad (9)$$

In the homogeneous case, the unstable eigenspace is actually two dimensional, and the reduced equation involves A , which is complex, and A^* ; since an equation similar to Eq. (8) can be written for $|A|$, we omit this slight difference here. In this case we have by symmetry $a_{2l} = 0$ for any $l \in \mathbb{N}^*$ and $a_{2l+1} \propto \lambda^{1-4l}$ [11], this strong divergence preventing the truncation of the series (8). By contrast, in the nonhomogeneous case, $a_2 \neq 0$; we show however below that a similar divergence pattern when $\lambda \rightarrow 0^+$ is expected. Nevertheless, keeping term up to A^2 , Eq. (8) looks like the normal form of a transcritical bifurcation; it is not a standard one, however, because λ is always positive, and a_2 diverges when $\lambda \rightarrow 0^+$. From the truncated equation, we can conjecture the following general phenomenology:

(i) On the unstable manifold, in one direction the dynamics is bounded and attracted by a stationary state close to f_μ , characterized by $A_\infty = -\lambda/a_2(\lambda)$ (notice that this state is stationary and stable for the truncated unstable manifold dynamics; it may not be so for the unconstrained dynamics).

(ii) In the other direction, the dynamics leaves the perturbative regime, and thus the range of validity of our analysis.

Estimating $a_2(\lambda)$ in the $\lambda \rightarrow 0^+$ limit gives access to A_∞ ; this requires more technical work, which is performed in the next section. Note that the formal computations leading to Eqs. (8) and (9) are essentially independent of the dimension; the following estimate for $a_2(\lambda)$ is valid in 1D.

B. Technical computation

We present now the explicit form of $a_2(\lambda)$, the order A^2 coefficient in the reduced dynamics, for the nonhomogeneous case of a generic one-dimensional system. The computation is somewhat technical, but the physical message is rather simple and is summarized here:

(i) $a_2 \propto 1/\lambda$ when $\lambda \rightarrow 0^+$.

(ii) The normalization condition requires $\tilde{\Psi}_\lambda = O(1/\lambda)$, and this divergence of the amplitude in the neighborhood of $\lambda = 0$ is responsible for the divergence of a_2 .

(iii) The integrals appearing in the scalar product in Eq. (9) do not diverge when $\lambda \rightarrow 0^+$.

The last two points are major differences with the homogeneous case in which the amplitude of $\tilde{\Psi}_\lambda$ does not diverge, and the resonances translate into pinching singularities for the integrals analogous to Eq. (9) [11]. These pinching singularities

are responsible for the divergences in the unstable manifold expansion. From these results, we can now conclude that the stationary state close to f_μ on the unstable manifold is characterized by $A_\infty \propto \lambda^2$, which is a central result of this article.

1. The spectrum matrix

Let us now turn to the explicit computation. We first need to introduce quantities regarding the linearized problem; we follow a classical method [20,21] and use here the notations of Ref. [22]. For preparation, we introduce the biorthogonal functions $\{d_i\}_{i \in I}$ and $\{u_k\}_{k \in K}$, on which we expand the density and potential, respectively,

$$\int f(q, p, t) dp = \sum_{i \in I} a_i(t) d_i(q), \quad (10)$$

$$V[f](q, t) = \sum_{k \in K} a_k(t) u_k(q). \quad (11)$$

The functions $\{d_i\}$ and $\{u_k\}$ satisfy

$$\int v(q - q') d_k(q') dq' = u_k(q), \quad (12)$$

and

$$(d_i, u_k) = \int d_i(q)^* u_k(q) dq = v_k \delta_{ik}. \quad (13)$$

The biorthogonal functions can be chosen to be real, and the factors v_k can be real accordingly. Their absolute values depend on the normalization choice for d_k , and hence only their signs [determined by two-body interaction $v(q)$] are meaningful.

In a generic system the spectrum function is a matrix denoted by $\Lambda_\mu(\lambda)$ [20,21], whose (l, k) element is

$$(\Lambda_\mu)_{lk}(\lambda) = v_k \delta_{lk} - 2\pi \sum_{m \in \mathbb{Z}} \int \frac{im \nabla_J F_\mu}{\lambda + im\Omega} c_{k,m} c_{l,m}^* dJ, \quad (14)$$

where we introduced the action-angle variables (J, θ) for an integrable Hamiltonian system $H[f_\mu]$ with one degree of freedom and assumed that f_μ depends only on J ; this is denoted by $f_\mu(q, p) = F_\mu(J)$. The function $c_{k,m}(J)$ is defined by

$$c_{k,m}(J) = \frac{1}{2\pi} \int u_k(q) e^{-im\theta} d\theta, \quad (15)$$

and the frequency $\Omega(J)$ by $\Omega = dH[f_\mu]/dJ$. We remark that $\det \Lambda_\mu(\lambda) = 0$ implies that λ is the eigenvalue of the linear problem. The matrix's size is $K \times K$, where K is the number of biorthogonal functions in the expansion of the potential; it is usually infinite but is only 2×2 for the cosine potential introduced later.

2. Properties of the spectrum matrix

To analyze Λ , we need to specify a little bit more the frequency $\Omega(J)$. We assume that $\Omega(J)$ does not vanish at finite J or does so only logarithmically. This includes the cases where the stationary potential $V[f_\mu](q)$ has a single minimum and is infinite for $|q|$ infinite (such as for 1D gravity), and the generic situation with periodic boundary conditions; indeed, in the latter situation, local minima of the stationary potential give rise to separatrices, on which the action is constant. At these specific values of the action Ω vanishes, but generically

it does so only logarithmically (an example of this situation is given in the next section). In particular, under the above assumption for Ω , the functions $(\Lambda_\mu)_{lk}(\lambda)$ defined in Eq. (14) are well defined for $\lambda = 0$ (the integral over J converges) and continuous for $\lambda \in \mathbb{R}$. Furthermore, the same reasoning applies to the derivatives of $(\Lambda_\mu)_{lk}(\lambda)$: these functions are continuous for $\lambda \in \mathbb{R}$, even for $\lambda = 0$. The fact that integrals over J converge is the technical counterpart of a physical phenomenon: the absence, or weakness, of resonances for $\lambda = 0$.

Furthermore, starting from Eq. (14), changing the summation variable m to $-m$, and using $c_{k,-m}(J) = c_{k,m}^*(J)$, it is not difficult to see that Λ_μ is a real matrix, and that $(\Lambda_\mu)_{lk}(\lambda) = (\Lambda_\mu)_{kl}(-\lambda)$. Hence $\Lambda_\mu(0^+)$ is symmetric. This will be useful below.

3. Comparison with the homogeneous case

The properties of the spectrum matrix detailed in the above paragraph are in sharp contrast with the better-known situation for a homogeneous stationary state. It is useful to highlight the comparison. We assume here periodic boundary conditions. For a homogeneous stationary state, a Fourier transform with respect to the space variable diagonalizes the spectrum matrix. The diagonal elements are [11]

$$\Lambda_k^{(\text{hom})}(\lambda) = 1 - 2i\pi k \hat{v}_k \int \frac{F_0'(p)}{\lambda + ikp} dp, \quad (16)$$

where $F_0(p)$ is the momentum distribution of the considered stationary state, and \hat{v}_k is the Fourier transform of the two-body potential. Note that, since $1/p$ is not integrable close to $p = 0$, Eq. (16) may not be well defined for $\lambda = 0$ and in any case is not differentiable along the imaginary axis. In particular, the function defined by Eq. (16) for $\lambda \in \mathbb{R}$ is not differentiable for $\lambda = 0$. This is the technical counterpart of the strong resonance phenomenon between a nonoscillating perturbation and particles with vanishing velocities. We come back now to the nonhomogeneous case.

4. Eigenfunctions

The eigenfunctions with eigenvalue λ of L_μ and L_μ^\dagger (recall that λ is real) are respectively expressed as

$$\Psi_\lambda = \sum_{k \in K} \sum_{m \in \mathbb{Z}} \frac{im \nabla_J F_\mu}{\lambda + im\Omega} c_{k,m} e^{im\theta} b_k, \quad (17)$$

and

$$\tilde{\Psi}_\lambda = - \sum_{k \in K} \sum_{m \in \mathbb{Z}} \frac{c_{k,m}}{\lambda - im\Omega} e^{im\theta} \tilde{b}_k, \quad (18)$$

where the real vectors $b = (b_k)$ and $\tilde{b} = (\tilde{b}_k)$ depending on λ must satisfy the conditions

$$\Lambda_\mu(\lambda) b(\lambda) = 0, \quad {}^T \tilde{b}(\lambda) \Lambda_\mu(\lambda) = 0, \quad (19)$$

and the upper T represents the transposition. Later we show that the normalization condition induces divergences of $\tilde{b}(\lambda)$ and accordingly of $a_2(\lambda)$ in the limit $\lambda \rightarrow 0^+$. The assumption that λ is a nondegenerate eigenvalue implies that $\dim \text{Ker} \Lambda_\mu(\lambda) = 1$. Otherwise, there would be two linearly independent eigenfunctions for λ .

5. Analysis of the a_2 coefficient

From the above eigenfunctions the $a_2(\lambda)$ term is written as

$$a_2(\lambda) = -2\pi \sum_{j \in K} \sum_{k \in K} \sum_{l \in K} \tilde{b}_j b_k b_l \times \sum_{m \in \mathbb{Z}} \sum_{n \in \mathbb{Z}} \int \frac{c_{j,m+n}^* \varphi_{m,n}}{\lambda + i(m+n)\Omega} dJ, \quad (20)$$

where

$$\varphi_{m,n} = \left[in \nabla_J \left(\frac{im \nabla_J F_\mu c_{k,m}}{\lambda + im\Omega} \right) c_{l,n} - \frac{im \nabla_J F_\mu c_{k,m}}{\lambda + im\Omega} im \nabla_J c_{l,n} \right]. \quad (21)$$

We study the λ dependence of the $a_2(\lambda)$ term in the limit $\lambda \rightarrow 0^+$.

First, we estimate the order of magnitude of \tilde{b} . The amplitude of b can be chosen arbitrarily but \tilde{b} cannot, since $\tilde{\Psi}_\lambda$ must satisfy the normalization condition, which is expressed as

$$1 = - \sum_{k \in K} \sum_{l \in K} \tilde{b}_l^* (\Lambda_\mu)'_{lk}(\lambda) b_k = - \langle \tilde{b}, \Lambda'_\mu(\lambda) b \rangle, \quad (22)$$

with $\langle \cdot, \cdot \rangle$ being the standard scalar product. Making use of the facts that the $(\Lambda_\mu)_{kl}$ are regular around $\lambda = 0^+$, the normalization condition reads

$$-1 = \langle \tilde{b}, \Lambda'_\mu(0) b_0 \rangle + \lambda \langle \tilde{b}, \Lambda''_\mu(0) b_0 + \Lambda'_\mu(0) b_1 \rangle + O(\lambda^2), \quad (23)$$

where we assumed that b can be expanded in λ :

$$b(\lambda) = b_0 + \lambda b_1 + O(\lambda^2). \quad (24)$$

We will show that the amplitude of $\tilde{b}(\lambda)$ diverges in the limit $\lambda \rightarrow 0^+$ and, accordingly, we assume that $\tilde{b}(\lambda)$ can be expanded as

$$\tilde{b}(\lambda) = \lambda^{-y} \tilde{Y}(\lambda), \quad \tilde{Y}(\lambda) = \tilde{b}_0 + \lambda \tilde{b}_1 + O(\lambda^2). \quad (25)$$

The normalization condition together with Eq. (25) imposes $y \geq 0$. First, we remark that $\det \Lambda_\mu(\lambda)$ is even in λ , and $\det \Lambda_{\mu_c}(0) = 0$; thus generically $\mu - \mu_c = O(\lambda^2)$. Therefore, we may replace μ_c by μ up to order λ . With this replacement, the definition of b reads, at order λ ,

$$\Lambda_\mu(0) b_1 = -\Lambda'_\mu(0) b_0. \quad (26)$$

Since $\Lambda_\mu(0)$ is symmetrical, this implies that $\Lambda'_\mu(0) b_0$ is orthogonal to the kernel of $\Lambda_\mu(0)$. Now, from the definition (19) of \tilde{b} , we obtain $\Lambda_\mu(0) \tilde{b}_0 = O(\lambda^2)$. Hence, we conclude that $\langle \tilde{b}_0, \Lambda'_\mu(0) b_0 \rangle = O(\lambda^2)$, and the first term of Eq. (23) is estimated as

$$\langle \tilde{b}(\lambda), \Lambda'_\mu(0) b_0 \rangle = O(\lambda^{1-y}). \quad (27)$$

The second term of Eq. (23) is also estimated in the same ordering as

$$\lambda \langle \tilde{b}, \Lambda''_\mu(0) b_0 + \Lambda'_\mu(0) b_1 \rangle = O(\lambda^{1-y}), \quad (28)$$

and the remaining terms are higher than $O(\lambda^{1-y})$. Consequently, to satisfy the normalization condition (23), the exponent y should be unity and $\tilde{b} = O(1/\lambda)$.

In order to show that \tilde{b} is the unique source of divergence in the $a_2(\lambda)$ term, we have to check two cases which may give an extra diverging factor $1/\lambda$ in the integrand of $a_2(\lambda)$ [see Eq. (20)]: $m = 0$ and $m + n = 0$. It is easy to find that the contribution from the former vanishes. Expanding $a_2(\lambda)$, we find that the contribution from the latter is canceled out at leading order between $\pm m$, and the integral gives a finite value. Therefore, we conclude that $a_2(\lambda)$ is of order $1/\lambda$ in the limit $\lambda \rightarrow 0^+$.

III. EXPLICIT EXAMPLE: COSINE POTENTIAL (HAMILTONIAN MEAN-FIELD MODEL)

The previous computations for a generic 1D potential are a bit abstract and complicated enough already at order A^2 . To perform higher-order computations and to prepare for precise numerical tests, we focus in this section on a particular interaction potential $v(q) = -\cos q$, with $q \in [0, 2\pi[$ and periodic boundary conditions; this model is sometimes called the Hamiltonian mean-field (HMF) model [23,24]. All computations then become more explicit, which will be useful to analyze higher orders; see Sec. III B. In addition, we can also make use in this context of the “rearrangement” approach described in Ref. [19]: this will provide an alternative analytical approach to test the results; see Sec. III C.

A. Cosine potential: computation at order A^2

The mean-field potential created by a phase-space distribution f is in this case $V_{MF}[f](q) = -M_x \cos q - M_y \sin q$, with

$$M = M_x + i M_y = \int \int f(q, p) e^{iq} dp dq.$$

M is usually called the “magnetization.” We choose M_μ , the magnetization of f_μ , to be real and assume a symmetric initial condition such that $M_y(t) = 0$ for all t [test simulations with $M_y(0) \neq 0$ —not shown—showed a similar behavior]. We also assume $M_\mu \neq 0$; that is, f_μ nonhomogeneous. The one-particle dynamics in V_{MF} is a simple pendulum dynamics, which is integrable; we introduce the associated action-angle variables (J, θ) .

The biorthogonal functions in the expansion of the potential are $\{\cos q, \sin q\}$, $v_1 = v_2 = -1$, and the size of matrix $\Lambda_\mu(\lambda)$ is 2 accordingly. The matrix $\Lambda(\lambda)$ is diagonal: $\Lambda_\mu(\lambda) = \text{diag}(\Lambda_\mu^c(\lambda), \Lambda_\mu^s(\lambda))$ [25], where [we have added for convenience an unimportant factor -1 with respect to Eq. (14)]

$$\Lambda_\mu^c(\lambda) = 1 + 2\pi \sum_{m \neq 0} \int \frac{im F'_\mu(J) |c_m(J)|^2}{\lambda + im\Omega(J)} dJ, \quad (29)$$

$$\Lambda_\mu^s(\lambda) = 1 + 2\pi \sum_{m \neq 0} \int \frac{im F'_\mu(J) |s_m(J)|^2}{\lambda + im\Omega(J)} dJ, \quad (30)$$

and

$$c_m(J) = \frac{1}{2\pi} \int_0^{2\pi} \cos q(\theta, J) e^{-im\theta} d\theta, \quad (31)$$

$$s_m(J) = \frac{1}{2\pi} \int_0^{2\pi} \sin q(\theta, J) e^{-im\theta} d\theta. \quad (32)$$

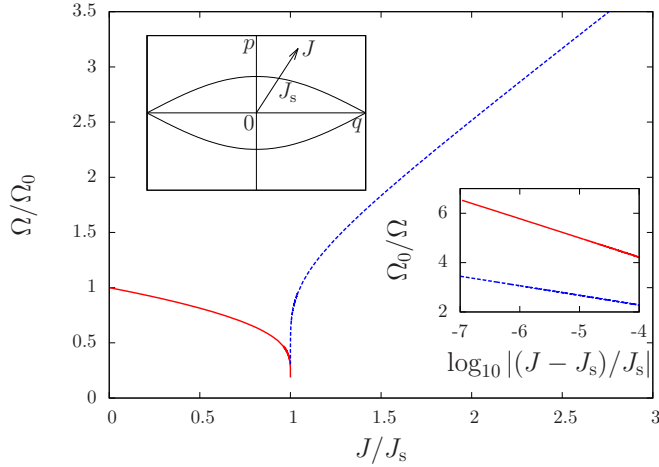


FIG. 1. Frequency Ω as a function of the action J in the HMF model. The action is J_s at the separatrix [see the upper-left inset representing the phase space (q, p)], where J_s is different if the separatrix is approached from below or from above [25]. Ω goes to Ω_0 in the limit $J \rightarrow 0^+$. The lower-right inset shows the logarithmic divergence of $1/\Omega$ around the separatrix action J_s for both inside (red solid upper line) and outside (blue broken lower line).

The spectrum function satisfies $\Lambda'_\mu(0) = 0$ [26], which corresponds to the Goldstone mode. The critical point μ_c is, therefore, determined by the other part and the root of the equation $\Lambda'_\mu(\lambda) = 0$ tends to 0^+ in the limit $\mu \rightarrow \mu_c$. Hereafter, we consider the cosine part Λ'_μ only and denote it by Λ_μ for simplicity.

In the above setting the eigenfunctions are

$$\Psi_\lambda = \sum_{m \in \mathbb{Z}} \frac{im F'_\mu(J) c_m(J)}{\lambda + im\Omega(J)} e^{im\theta}, \quad (33)$$

$$\tilde{\Psi}_\lambda = -\frac{1}{\Lambda'_\mu(\lambda)^*} \sum_{m \in \mathbb{Z}} \frac{c_m(J)}{\lambda - im\Omega(J)} e^{im\theta}. \quad (34)$$

It is easy to see that $\Lambda'_\mu(\lambda) \sim C\lambda$ for $\mu \rightarrow \mu_c$, inducing a divergence in $\tilde{\Psi}_\lambda$, which was implicitly included in \tilde{b} in the generic setting; see Eq. (18) and the conclusion for the order of magnitude of \tilde{b} below Eq. (28). The possibility of resonances is readily seen in Eqs. (33) and (34): they correspond to actions J such that $\lambda \pm im\Omega(J) = 0$. Since we have assumed $\lambda \in \mathbb{R}$, this can happen only at the separatrix $J = J_s$, where $\Omega(J_s) = 0$ (see Fig. 1). The divergence is very weak, $\Omega(J)^{-1} = O(\ln|J - J_s|)$, thus *resonances are strongly suppressed* since the number of particles around $J = J_s$ is negligible. On the other hand, for a complex λ strong resonances are possible, *a priori* similar to those occurring in the homogeneous case.

For the cosine potential (HMF model), the above expression (20) for $a_2(\lambda)$ simplifies a little bit:

$$a_2(\lambda) = \frac{-2\pi}{\Lambda'_\mu(\lambda)} \int \sum_{m,n \in \mathbb{Z}} \frac{c_{m+n}^* \varphi_{m,n}(J)}{\lambda + i(m+n)\Omega} dJ, \quad (35)$$

where $\Lambda_\mu(\lambda)$ is given by Eq. (29), and

$$\varphi_{m,n}(J) = m \left[n \frac{\partial}{\partial J} \left(\frac{F'_\mu c_m}{\lambda + im\Omega} \right) c_n - m \frac{F'_\mu c_m}{\lambda + im\Omega} c'_n \right]. \quad (36)$$

It is straightforward to see that $a_2(\lambda)$ is of order $1/\lambda$ in the limit $\lambda \rightarrow 0^+$ due to the divergent factor $1/\Lambda'_\mu(\lambda)$. Some details on how to compute numerically with good accuracy the function Λ_μ and its roots are given in Appendix A.

B. At order A^3

We can extend the above computations to higher orders. While the structure is standard, the effective computations are intricate, hence the details are placed in Appendix B. Concentrating on the cosine-potential case, we obtain the result $a_3 \sim C/\lambda^3$ as $\lambda \rightarrow 0^+$, which is the same divergence strength as the one appearing in the homogeneous case [27], although the mechanism inducing the divergence is different.

C. Rearrangement formula for the cosine potential

The rearrangement formula is a powerful tool to predict the asymptotic stationary state f_μ^A from a given initial state f_μ . We show here that it allows us to recover some of the above results, following a very different route.

The main result from the rearrangement formula is, roughly speaking,

$$f_\mu^A = \langle f_\mu \rangle_A, \quad (37)$$

where the symbol $\langle \cdot \rangle_A$ represents the average over angle variable at fixed action, with angle and action being associated with the asymptotic Hamiltonian $H_\mu^A = H[f_\mu^A]$ whose potential part is determined self-consistently [19]. We show that this formula predicts $|M_\mu^A - M_\mu| = O(\lambda^2)$, where M_μ and M_μ^A are magnetizations in f_μ and f_μ^A , respectively: this is consistent with the unstable-manifold analysis.

We assume that $f_\mu = F_\mu(H_\mu)$. The average $\langle \cdot \rangle_A$ can be removed when applied to any function of energy: $\langle \varphi(H_\mu^A) \rangle_A = \varphi(H_\mu^A)$ by the definition [19]. Thus, we can expand $\langle f_\mu \rangle_A$ with respect to small $\delta H = H_\mu^A - H_\mu$ and have

$$f_\mu^A = f_\mu + F'_\mu(H_\mu) \delta H - F'_\mu(H_\mu^A) \langle \delta H \rangle_A + \dots \quad (38)$$

Adding and subtracting $F'(H_\mu) \langle \delta H \rangle_A$ where the average $\langle \cdot \rangle_A$ is taken over angle variable associated with H_μ , multiplying by $\cos q$, and integrating over (q, p) , we obtain a self-consistent equation for $\delta M = M_\mu^A - M_\mu$:

$$\Lambda_\mu(0) \delta M + \mathcal{N}(\delta M) = 0, \quad (39)$$

where $\mathcal{N}(\delta M)$ is of higher order and we used Parseval's equality [28] to derive the coefficient $\Lambda_\mu(0)$. Straightforward computations give

$$\mathcal{N}(\delta M) = \begin{cases} O((\delta M)^{3/2}) & (M_\mu = 0) \\ O((\delta M)^2) & (M_\mu \neq 0), \end{cases} \quad (40)$$

where the homogeneous case is rather singular [29], and the leading nonzero solution to Eq. (39) is

$$\delta M = \begin{cases} O(\Lambda_\mu(0)^2) & (M_\mu = 0) \\ O(\Lambda_\mu(0)) & (M_\mu \neq 0). \end{cases} \quad (41)$$

The relation between $\Lambda_\mu(0)$ and the instability rate λ is obtained by recalling that λ satisfies $\Lambda_\mu(\lambda) = 0$ and expanding

$\Lambda_\mu(\lambda)$ with respect to λ . This expansion implies

$$\Lambda_\mu(0) = \begin{cases} O(\lambda) & [\Lambda'_\mu(0) \neq 0] \\ O(\lambda^2) & [\Lambda'_\mu(0) = 0 \text{ and } \Lambda''_\mu(0) \neq 0], \end{cases} \quad (42)$$

and the former and the latter correspond to the homogeneous and nonhomogeneous cases, respectively. Summarizing, the rearrangement formula gives the scaling $\delta M = O(\lambda^2)$ for both homogeneous and nonhomogeneous cases, although the mechanisms for these scalings are different in each case, as already found in the unstable-manifold reduction. We remark that, in the nonhomogeneous case, the leading three terms of Eq. (39) give two nonzero solutions of order $O(\lambda^2)$ and $O(1)$, whose stability is not clear by the rearrangement formula only. The latter solution is *a priori* out of range of the method; nevertheless, later we will numerically observe that one direction of perturbation drives the system to the $O(\lambda^2)$ state, and the other direction to $O(1)$.

IV. DIRECT NUMERICAL SIMULATIONS

Our analytical description of the bifurcation can be accurately tested in the HMF case. The time-evolved distribution function is obtained via a GPU (graphics processing unit) parallel implementation of a semi-Lagrangian scheme for the Vlasov HMF equation with periodic boundary conditions [30]. We use a $2^n \times 2^n$ grid in position-momentum phase space truncated at $|p| = 2$ with n up to 12; the time step is usually 10^{-2} . We use two families of reference stationary states:

$$F_\mu^0(\mathcal{E}) = N_F^{-1} / [1 + e^{\beta(\mathcal{E}-\mu)}], \quad G_\mu^0(\mathcal{E}) = N_G^{-1} \mathcal{E}^2 e^{-\mu\mathcal{E}}, \quad (43)$$

with the one-particle energy $\mathcal{E}(q, p) = p^2/2 + M_\mu[1 - \cos(q)]$, where the magnetization M_μ has to be computed self-consistently, and N_F and N_G are the normalization factors. Figure 2 presents M_μ and its bifurcations for the family F_μ^0 . For both families, a real positive eigenvalue appears at a

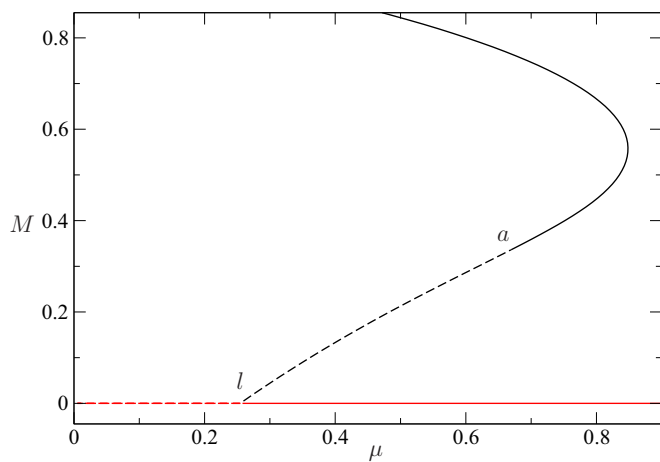


FIG. 2. Phase diagram of the Fermi distribution F_μ^0 with $\beta = 40$. Dotted lines correspond to unstable stationary solutions and solid lines correspond to stable ones. We are interested in this article in the neighborhood of point *a*, where a branch of stable inhomogeneous $M_\mu \neq 0$ stationary solutions becomes unstable. At point *l*, a branch of stable homogeneous stationary solutions ($M_\mu = 0$, red solid line) becomes unstable; we do not consider this bifurcation in this article.

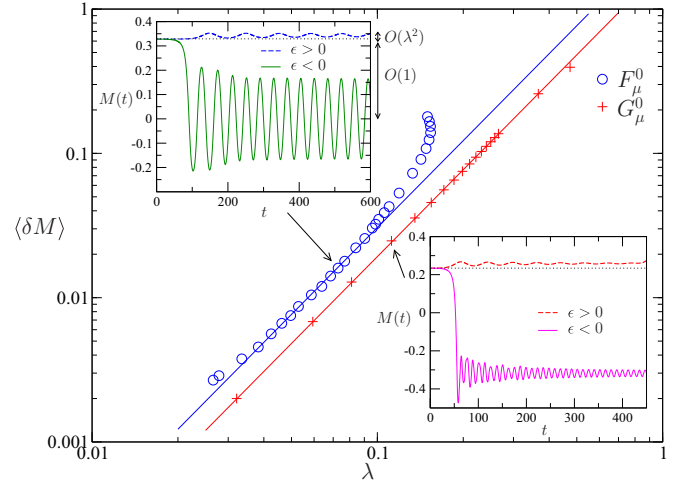


FIG. 3. $\langle \delta M \rangle(\lambda)$ for F_μ^0 (circles) and G_μ^0 (crosses) with associated quadratic fit; $\beta = 40$. For each function we show two runs of $M_x(t) = M(t)$ [here $M_y(t) = 0$] with positive and negative ϵ . $\langle \delta M \rangle$ in the main diagram is computed as a long-time average for $\epsilon > 0$. For F_μ^0 , $|\epsilon| = 1.8 \times 10^{-6}$; for G_μ^0 , $|\epsilon| = 10^{-5}$, except for $\lambda = 0.032$ where $|\epsilon| = 3 \times 10^{-6}$. Note that the reference stationary states F_μ^0 follow the curve from point *a* towards point *l* on Fig. 2. Along this curve, λ starts from 0 at point *a* then grows and reaches an upper limit, about 0.15, before decreasing and reaching 0 again at point *l*. This is why two values of μ may correspond to the same value of λ (but different values of $\langle \delta M \rangle$), as can be seen around $\lambda = 0.15$.

critical value of μ : for F_μ^0 , this is at point *a*; see Fig. 2. The initial perturbation is $\epsilon T(q, p) = \epsilon \cos(q) \exp(-\beta p^2/2)$. Note that this is not proportional to the unstable eigenvector Ψ_λ : this allows us to test the robustness of our unstable-manifold analysis with respect to the initial condition. For all simulation results presented in Fig. 3, the size of the perturbation ϵ was chosen small enough such that the saturated solution reached for $\epsilon > 0$ does not depend on ϵ . On the other hand, the smaller is ϵ , the more accurate computations are required to avoid numerical errors. In particular, we observe that numerical errors may drive the system far away from the reference stationary solution, following a dynamics similar to that with $\epsilon < 0$. In such cases, we used a finer phase-space grid: GPU computational power was crucial to reach very fine grids. For example, the initial Fermi distribution F_μ^0 was very sensitive to numerical errors and to ϵ : we took $\epsilon = 1.8 \times 10^{-6}$ with a 4096×4096 grid; for G_μ^0 distribution, which is much smoother, $\epsilon = 10^{-5}$ and a 1024×1024 grid was enough (except for the point corresponding to $\lambda = 0.032$ where more precision was needed, and we took $\epsilon = 3 \times 10^{-6}$).

Typical evolutions for the order parameter $M(t)$ are shown in Fig. 3 (insets) for positive and negative ϵ . The asymmetry is clear: for one perturbation the change in $\delta M = M(t) - M_\mu$ remains small; for the other it is $O(1)$. In the case where δM remains small, we compute its saturated value by averaging the small oscillations; the result is plotted as a function of λ in Fig. 3: the $\delta M \propto \lambda^2$ behavior is clear for both families. The fact that numerical simulations are able to reach this stationary state suggests that it is a genuine stationary state, indeed stable with respect to the whole dynamics, and not only on the unstable

manifold. However, longer simulations, or with smaller grid sizes (not shown), indicate it is also easily destabilized by numerical noise. We conclude that the $O(\lambda^2)$ state is thus probably close to the instability threshold. Notice that, for the initial unstable reference state, $|\Lambda_\mu(0)| = O(\lambda^2)$ is very small; hence the very close nearby stationary state with $\delta M \propto \lambda^2$ may have a different stability, although (in)stability of nonhomogeneous stationary states is rather robust comparing with the homogeneous case (see Ref. [31] for a discussion).

We provide as supplementary material three videos [32] to better illustrate the phase-space dynamics. The video “BarreMetivierYamaguchi_eps_plus.mp4” shows the time evolution of the distribution function in phase space with initial condition $F_\mu^0(\mathcal{E}(q, p)) + \epsilon T(q, p)$, for $\epsilon = +1.8 \times 10^{-6}$, $\beta = 40$, ($M_\mu = 0.328$, $\mu = 0.658$) (it corresponds to the dashed blue curve in the upper inset of Fig. 3) from $t = 0$ to $t = 600$. Since the system reaches a new stationary state close to the original one, we observe almost no change in the distribution function. It is important to notice, however, that this picture is very different from that of the saturation of an instability over an homogeneous background: in that case, resonances would create small “cat eye” structures, which do not appear here. To better appreciate the dynamics in this case, we also provide the video “BarreMetivierYamaguchi_eps_plus_diff.mp4,” which is the same as the previous one except that the reference state F_μ^0 has been subtracted; hence the evolution of the perturbation is more clearly shown.

The video “BarreMetivierYamaguchi_eps_minus.mp4” shows the time evolution of the distribution function with the same parameter values except that $\epsilon = -1.8 \times 10^{-6}$ (it corresponds to the green curve in the upper inset of Fig. 3). This time the distribution changes completely its shape and seems to approach a periodic solution, far away from the original stationary distribution. In all simulations the relative error between the total energy of the system at a given time and the total initial energy is at most of the order of 10^{-7} .

V. CONCLUSION

To summarize, we have elucidated for one-dimensional Vlasov equations the generic dynamics of a nonoscillating instability of a nonhomogeneous steady state. We have shown in particular the following: (i) Due to the absence of resonances, the physical picture is very different from the homogeneous case. (ii) A striking asymmetry: in one direction on the unstable manifold, the instability quickly saturates, and the system reaches a nearby stationary state. In the other direction the instability does not saturate, and the dynamics leaves the perturbative regime. (iii) For an instability rate λ , the nearby stationary state is at distance $O(\lambda^2)$ from the original stationary state. Direct numerical simulations of the Vlasov equation with a cosine potential confirm these findings, and furthermore suggest that this phenomenology may have relevance for initial conditions that are not on the unstable manifold.

These results are generic for 1D Vlasov equations. It will be important to assess if they can be extended to two- and three-dimensional systems. The structure of the reduced equation on the unstable manifold, which underlies the asymmetric

behavior, should be valid in any dimension. However, the crucial physical ingredient underlying our detailed computations leading to the $O(\lambda^2)$ scaling is the absence (or the weak effect) of resonance between the growing mode and the particles’ dynamics. This has to be carefully analyzed in higher dimensions and is left for a future study. Let us note that the findings of Ref. [13] regarding the nonlinear evolution of the radial orbit instability are in agreement with this picture: they start from a weakly unstable spherical state; close to this reference state, they find an axisymmetric weakly oblate stationary state; at finite distance from the reference state (outside the perturbative regime), they find a stable prolate stationary state. This is consistent with the asymmetric behavior we predict on the unstable manifold. An open question regards the stability of the new weakly oblate stationary state: in our numerical examples, it seems stable, but very close to threshold. In Ref. [13] they claim it is unstable, but since their numerical simulations are much less precise, this could be a numerical artifact.

Finally, let us mention other open problems raised by this work: is it possible to derive an infinite-dimensional reduced dynamics, as in Ref. [12]? In the homogenous case and on the stable side of the bifurcation [i.e., with $\text{Re}(\lambda) < 0$], Lancellotti and Dornig in Ref. [33] have shown the existence of “critical initial states” separating solutions that fully damp from solutions with a nontrivial asymptotic force; do they extend to inhomogeneous states? We have also restricted ourselves in this article to a real unstable eigenvalue. It is obviously worthwhile to investigate the bifurcation with a complex pair of eigenvalues. Resonances should appear in this case, similar to those in the homogeneous case, but with a different symmetry: new features are thus expected.

ACKNOWLEDGMENTS

D.M. thanks T. Rocha for providing his GPU Vlasov-HMF solver. Y.Y.Y. acknowledges the support of JSPS KAKENHI Grant No. 23560069. J.B. acknowledges the hospitality of Imperial College, where part of this work was performed.

APPENDIX A: COMPUTING THE FUNCTION $\Lambda_\mu(\lambda)$ AND ITS ROOTS

Testing the predicted scaling $A_\infty \propto \lambda^2$, as done in Sec. IV, requires computing λ with good accuracy. We present our method in this appendix. To compute the eigenvalue λ associated with a given initial distribution $f_\mu(q, p) = F_\mu(J)$, one has to find a positive root of the dispersion function

$$\Lambda_\mu(\lambda) = 1 + 2\pi \sum_{m \neq 0} \int \frac{im F'_\mu(J) |c_m(J)|^2}{\lambda + im\Omega(J)} dJ. \quad (\text{A1})$$

The two main numerical obstacles are to compute efficiently the functions $c_m(J)$, and the infinite sum in m . Fourier expansions of sn^2 (sn is the sine Jacobi elliptic function) are known [34] and can be used with Ref. [28] to obtain the

following expressions:

$$c_0(k) = \begin{cases} \frac{2E(k)}{K(k)} - 1, & k < 1 \\ \frac{2k^2 E(1/k)}{K(1/k)} + 1 - 2k^2, & k > 1, \end{cases} \quad (\text{A2})$$

and for $m \neq 0$,

$$\begin{cases} c_{2m}(k) = \frac{2\pi^2}{K(k)^2} \frac{mq(k)^m}{1 - q(k)^{2m}}, & k < 1 \\ c_{2m+1}(k) = 0, & k < 1 \\ c_m(k) = \frac{2\pi^2 k^2}{K(1/k)^2} \frac{mq(1/k)^m}{1 - q(1/k)^{2m}}, & k > 1, \end{cases} \quad (\text{A3})$$

where $K(k)$ and $E(k)$ are the elliptic functions of first and second kind, respectively, and $q(k) = \exp[-\pi K(\sqrt{1-k^2})/K(k)]$. Note that one may also use the $\text{sn} \times \text{dn}$ and $\text{sn} \times \text{cn}$ Fourier expansions to obtain similar expressions for the Fourier transform of $\sin q$ with respect to θ . These explicit expressions allow efficient computations of c_m and help in choosing a right truncation for the m summation. A standard numerical solver then provides precise values of λ . Summing in Eq. (A1) $c_{2m}(J)$ (when $J < J_s$) and $c_m(J)$ (when $J > J_s$) up to $|m| = 9$ ($|m| = 7$) for F_μ^0 (G_μ^0) is enough to compute λ with six-digit accuracy.

APPENDIX B: COMPUTATIONS AT HIGHER ORDERS

We explain here how to compute the higher-order terms. Section B1 is valid for a general potential, but to explicitly work out the order of magnitude of a_3 , we restrict ourselves to the cosine potential. We then show that $a_3 \sim C/\lambda^3$ as $\lambda \rightarrow 0^+$.

1. Structure of the computation for a general potential

Let us parametrize the unstable manifold of f_μ as

$$g = \sum_{k \geq 1} S_k A^k, \quad S_1 = \Psi_\lambda. \quad (\text{B1})$$

Since the nonlinear part $N[g]$ of the Vlasov equation, $\partial_t g = L_\mu g + N[g]$, is bilinear, we write it as

$$N[g] = B(g, g), \quad \text{with } B(g, h) = \partial_J g \partial_\theta V[h] - \partial_\theta g \partial_J V[h].$$

Recalling that the reduced dynamics on the unstable manifold is

$$\dot{A} = \sum_{k \geq 1} a_k A^k, \quad a_1 = \lambda, \quad (\text{B2})$$

our goal is to provide a formal expression for a_k . This requires computing at the same time the S_k s. We write the time evolution equation for g in two ways:

$$\begin{aligned} \partial_t g &= \sum_{k \geq 1} \sum_{l \geq 1} A^{k+l-1} k a_l S_k \\ &= \sum_{k \geq 1} A^k L_\mu S_k + \sum_{k \geq 1} \sum_{l \geq 1} A^{k+l} B(S_k, S_l), \end{aligned} \quad (\text{B3})$$

where we have used (B2). Picking up the terms order by order, we have for any k

$$(k a_1 - L_\mu) S_k = \sum_{l=1}^{k-1} [B(S_{k-l}, S_l) - (k-l) a_{l+1} S_{k-l}]. \quad (\text{B4})$$

This equation for $k = 1$ is simply $L_\mu \Psi_\lambda = \lambda \Psi_\lambda$, and we focus on $k \geq 2$.

We now project these equations onto $\text{Span}\{\Psi_\lambda\}$ and $\text{Span}\{\Psi_\lambda\}^\perp$; we note the corresponding projection operators Π and $\Pi^\perp = \mathbb{I} - \Pi$, where \mathbb{I} is the identity. The projection operators work as

$$\begin{aligned} (\Pi \circ L_\mu) \Psi_\lambda &= \lambda \Psi_\lambda, \quad (\Pi^\perp \circ L_\mu) \Psi_\lambda = 0, \\ (\Pi \circ L_\mu) S_k &= 0, \quad (\Pi^\perp \circ L_\mu) S_k = L_\mu S_k, \quad k \geq 2. \end{aligned} \quad (\text{B5})$$

The projection operator Π induces

$$a_k \Psi_\lambda = \sum_{l=1}^{k-1} \Pi \circ B(S_{k-l}, S_l), \quad (\text{B6})$$

and Π^\perp yields

$$(k\lambda - L_\mu) S_k = \sum_{l=1}^{k-1} \Pi^\perp \circ B(S_{k-l}, S_l) - \sum_{l=1}^{k-2} (k-l) a_{l+1} S_{k-l}. \quad (\text{B7})$$

Equation (B6) determines a_k from S_l , and Eq. (B7) determines S_k from S_l and a_l with $l \in \{1, \dots, k-1\}$.

2. Cosine potential: Order of magnitude of a_3

We now specialize in the cosine potential and focus on the third-order coefficient a_3 .

Calling G_k the right-hand side (r.h.s.) of Eq. (B7), we have

$$S_k = R(k\lambda) G_k, \quad (\text{B8})$$

where $R(z) = (z - L_\mu)^{-1}$ is the resolvent of L_μ . Our first task is to determine the λ dependence of $R(k\lambda) G_k$. Let us then consider the equation

$$(z - L_\mu) X = G,$$

and solve for $X(\theta, J)$. Denoting the m th Fourier component of X in θ as \hat{X}_m , we find after some computations, for all $m \in \mathbb{Z}$,

$$\hat{X}_m = \frac{\hat{G}_m}{z + im\Omega(J)} - C(z) \frac{imc_m F'_\mu(J)}{z + im\Omega(J)}, \quad (\text{B9})$$

where

$$C(z) = \frac{2\pi \sum_l \int \frac{\hat{G}_l c_l^*}{z + il\Omega(J')} dJ'}{\Lambda_\mu(z)}. \quad (\text{B10})$$

Taking $z = 2\lambda$ in Eq. (B9), we see that $\Lambda_\mu(2\lambda)^{-1}$ introduces a $1/\lambda^2$ divergence, and that the $l = 0$ term in the sum yields an extra $1/\lambda$ divergence, unless $\hat{G}_{l=0} = 0$. Thus, the C factor (B10) gives the leading singularity.

Now, recalling (B7), we have to apply the resolvent to $G = \Pi^\perp B(\Psi_\lambda, \Psi_\lambda)$. Using the definition of a_2 , we have

$$S_2 = R(2\lambda) B(\Psi_\lambda, \Psi_\lambda) - a_2 R(2\lambda) \Psi_\lambda. \quad (\text{B11})$$

We first note that $B(\widehat{\Psi_\lambda}, \widehat{\Psi_\lambda})_{m=0} = 0$ (B contains two terms, each containing a derivative with respect to θ ; hence the

zeroth Fourier mode vanishes) and that $\hat{\Psi}_{\lambda,m=0} = 0$. Hence the possible divergence related to $l = 0$ in Eq. (B9) does not exist, and the resolvent introduces only a $1/\lambda^2$ divergence. We conclude that, in the r.h.s. of Eq. (B11), the first term is $O(\lambda^{-2})$. The second is *a priori* $O(\lambda^{-3})$, since $a_2 \propto 1/\lambda$, but we show now it is actually also $O(\lambda^{-2})$. The C factor (B10) for $(\hat{R}(2\lambda)\Psi_\lambda)_m$ is

$$\begin{aligned} C &= \frac{2\pi \sum_m \int \frac{\hat{\Psi}_m c_m^*}{2\lambda + im\Omega(J)} dJ}{\Lambda_\mu(2\lambda)} \\ &= \frac{2\pi}{\Lambda_\mu(2\lambda)} \sum_m \int im \frac{F'_\mu(J) |c_m|^2}{(\lambda + im\Omega)[2\lambda + im\Omega(J)]} dJ \\ &= \frac{2\pi}{\Lambda_\mu(2\lambda)} 6\lambda \sum_{m>0} \int m^2 \frac{F'_\mu(J) |c_m|^2}{|\lambda + im\Omega|^2 |2\lambda + im\Omega|^2} dJ \sim \frac{3}{2} \frac{\Lambda'_\mu(\lambda)}{\Lambda_\mu(2\lambda)} = O(1/\lambda), \end{aligned}$$

where the last line is for $\lambda \rightarrow 0^+$. Hence, the second term on the r.h.s. of Eq. (B11) is $O(\lambda^{-2})$, and so is S_2 . From Eq. (B6)

$$a_3 \Psi_\lambda = \Pi \circ [B(S_2, \Psi_\lambda) + B(\Psi_\lambda, S_2)], \quad (\text{B12})$$

where the r.h.s. is Π applied to a $O(\lambda^{-2})$. Now, the projection Π contains a diverging $1/\lambda$ factor, coming from the normalization

factor $1/\Lambda'_\mu(\lambda)$, needed in $\tilde{\Psi}_\lambda$ to ensure that $\langle \tilde{\Psi}_\lambda, \Psi_\lambda \rangle = 1$. Hence, except for a restricted set of functions φ such that $\langle \tilde{\Psi}_\lambda, \varphi \rangle = O(1)$, we have (for φ independent of λ) $\Pi\varphi \propto 1/\lambda$. The exceptional φ such that the projection Π does not introduce a diverging $1/\lambda$ factor lie close to the kernels of Π and Π^\perp [the latter is just $\text{Span}(\Psi_\lambda)$]. With this in mind, it is not difficult to conclude that $a_3 \propto 1/\lambda^3$.

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